



AMD Socket 940 Design Specification



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Revision History

Date	Revision	Changes
September 2003	3.03	Third public release.
September 2003	3.02	Internal revision.
May 2003	3.01	Second public release.
April 2003	3.00	Initial public release.

1 Introduction

This document defines the requirements for a 940-pin, 1.27-mm pitch, surface mount technology (SMT), zero insertion force (ZIF) socket (herein referred to as “Socket 940”) for use with Advanced Micro Devices (AMD) 940-pin ceramic micro pin grid array (μ PGA) package. Socket 940, shown in Figure 1, provides a reliable electrical interconnect between the printed circuit board (PCB) and the 940 pins of the ceramic μ PGA package, throughout the life of the product.

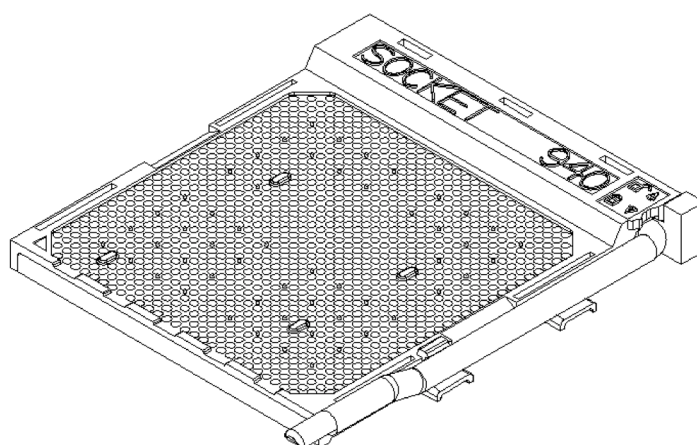


Figure 1. A 3-D View of Socket 940.

1.1 Purpose

This document specifies the dimensional, mechanical, electrical, and reliability requirements for the Socket 940 that are necessary to meet the performance requirements of AMD Athlon™ 64 FX processor or AMD Opteron™ processor products.

1.2 Supplier Requirements

To become an AMD qualified supplier for Socket 940, the potential socket supplier shall demonstrate that their product meets the requirements listed in this document and by conducting qualification testing on their production run sockets in accordance with the AMD Socket 940 Qualification Plan.

2 Microprocessor Package Description

This chapter provides dimensional information for the 940-pin ceramic μ PGA package that mates with Socket 940.

2.1 940-pin Ceramic μ PGA Package

The 940-pin ceramic μ PGA package drawing is shown in Figure 2.

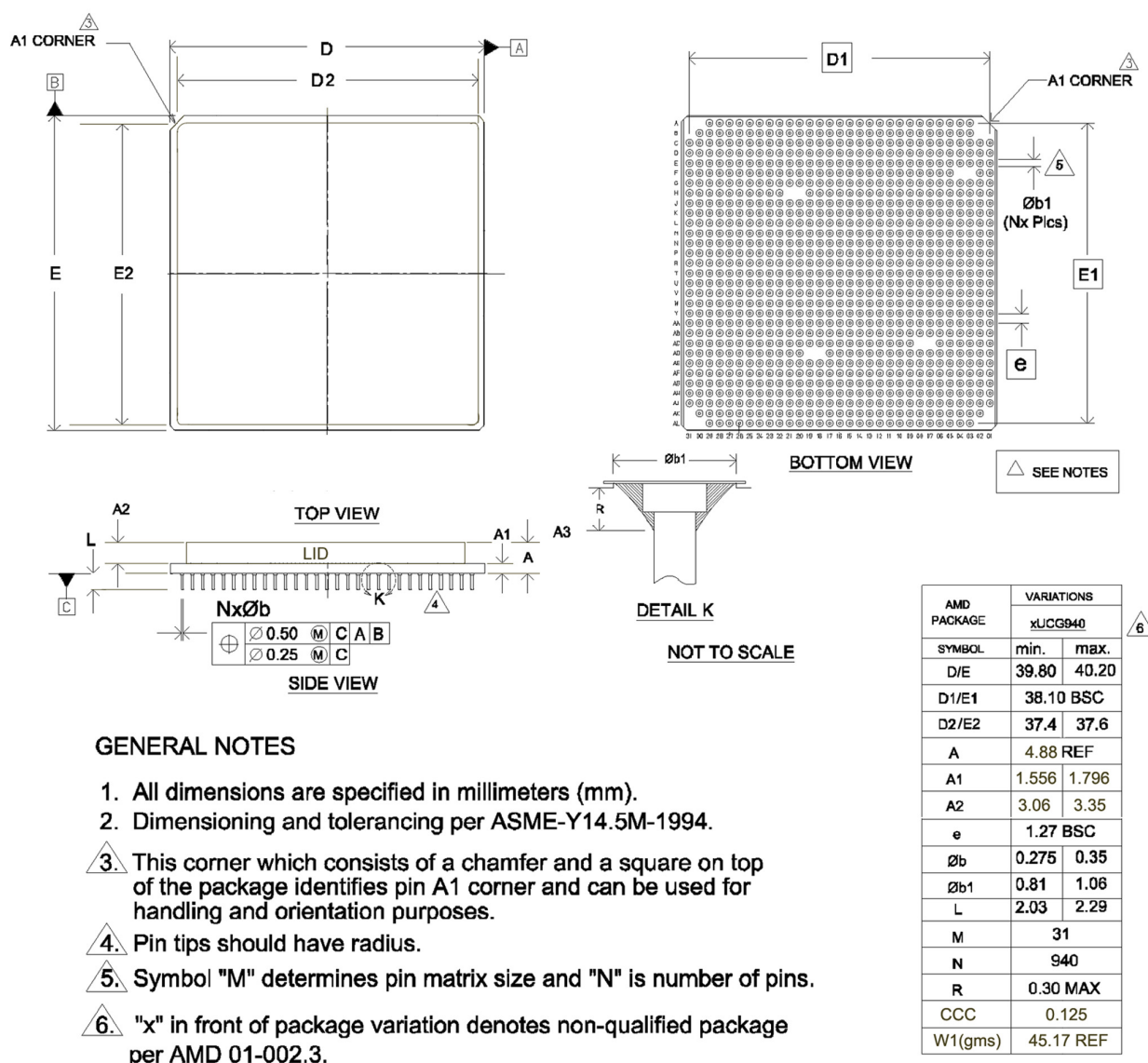


Figure 2. 940-Pin Ceramic μ PGA Package Drawing

2.2 Package Substrate and Pin Dimensions.

The package substrate and pin dimensions, tolerances, and true position parameters are shown in Figure 2 on page 9.

Socket 940 is designed to be functional with the lidded, as well as with the lidless package configuration. The total package thickness for the lidless configuration is 2.20 mm minimum.

3 Socket Mechanical Requirements

This chapter discusses the socket outline and mechanical requirements for the Socket 940.

3.1 Socket Outline

Figure 3 shows the allowable outline for the Socket 940. All dimensions shown are in millimeters.

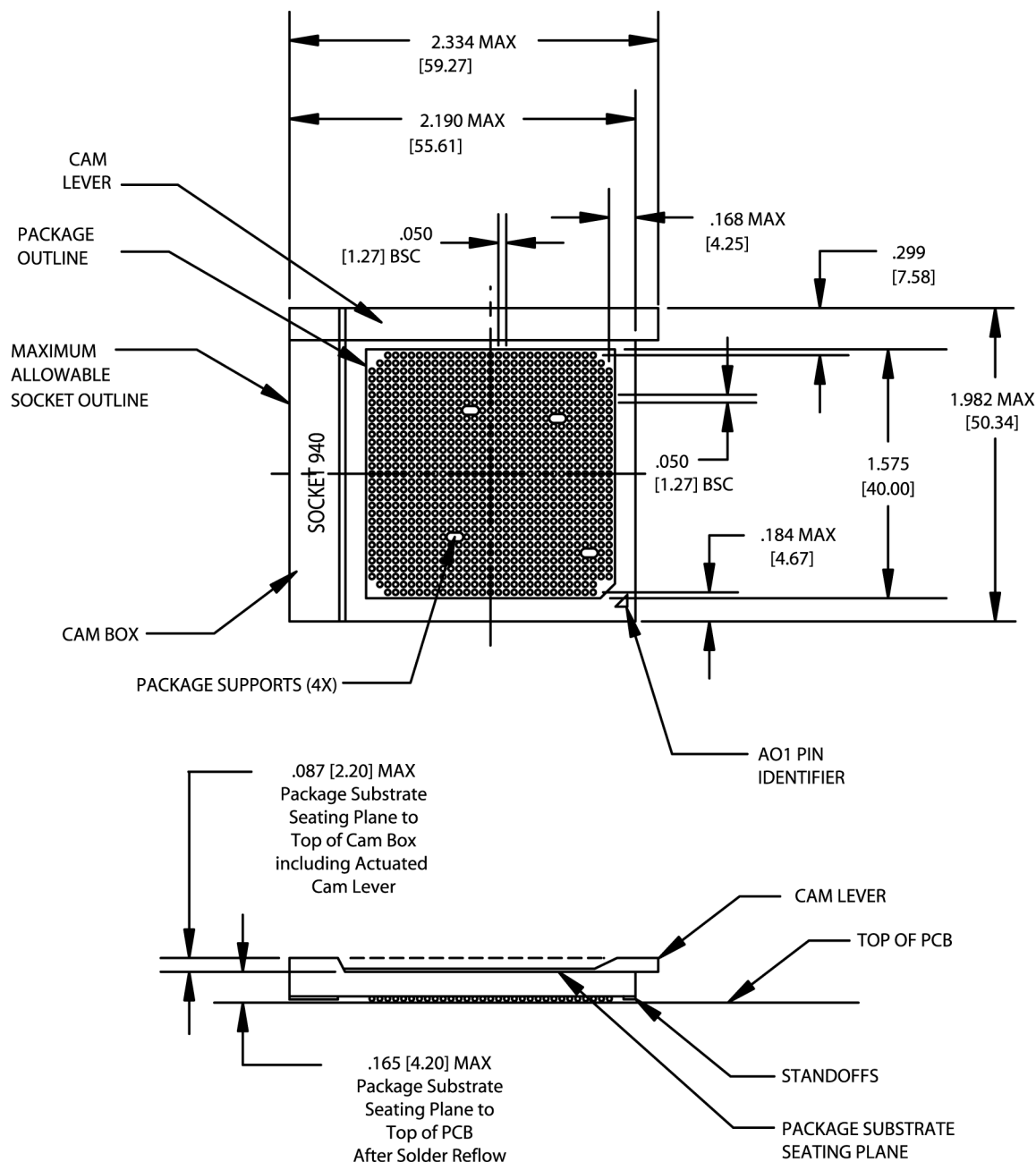


Figure 3. Socket 940 Outline

3.2 Package Seating Plane

The cover for the Socket 940 is designed to accommodate the package pin shoulder and braze/solder fillet as shown by the 940-pin ceramic μ PGA package drawings in Figure 2. Support structures are incorporated into the socket cover to provide sufficient mechanical support (seating plane) for the package substrate, without causing damage to the package pins at any time.

The package-seating plane on the socket cover has a surface flatness better than 0.25 mm, when unmated as well as when mated with a package. After socket mounting to the printed circuit board (PCB), the package-seating plane on the socket cover is 4.00 ± 0.20 mm from the mounting surface of the PCB.

3.3 Socket Base and Cover

The socket base and socket cover are made from Liquid Crystal Polymer (LCP) with a UL flammability rating of 94 V-0. The base color is black and the cover color is natural or ivory.

The thickness of the socket cover (including the 0.30 mm pocket recess) must not exceed 1.17 mm. The socket cover flatness is less than 0.25 mm, before and after the SMT reflow to the PCB. The flatness measurement must remain less than 0.25 mm after environmental and mechanical testing.

Either a removable tape or plastic cover acts as an overlay for the pin holes in the top of the socket cover. The overlay facilitates socket pick-and-place operation with a vacuum nozzle during board assembly. The overlay must not outgas during the solder reflow processes or leave any residue upon removal prior to package pins insertion.

3.3.1 Socket Markings

The socket identifier marking “SOCKET 940” must be molded into the top surface of the socket cover cam box region, where the number 940 represents the pin count of the mating ceramic μ PGA package (see Figure 1 on page 7).

A locked and unlocked directional designator is molded into the top surface of the cam box, in close proximity to the actuation lever. See Figure 1 on page 7.

A triangular shape symbol must be molded into the top of the socket cover for proper package pin A01 orientation. This orientation symbol is located to remain visible after the package is mated to the socket as shown in Figure 1 on page 7 and Figure 3 on page 11.

The supplier’s UL approved symbol is molded on the socket cover. This marking is located such that it remains visible and readable after the socket is solder mounted onto the PCB.

The lot traceability number can be ink, laser, or impact marked on the socket cover. This marking must be located to be visible and readable after the socket is solder mounted onto the PCB.

3.4 Socket Contact

This section describes the contact material and solder balls for socket attachment to the PCB.

Note: *No lubricants can be present on the contact mating areas of fully assembled sockets that are shipped to customers by the supplier.*

3.4.1 Contact Base Metal

The contact base metal is high-strength copper alloy.

3.4.2 Contact Plating

The entire contact is plated with 1.27- μ m minimum thickness of nickel.

The contact mating area is plated with 0.76- μ m minimum thickness of gold over the 1.27 μ m minimum thickness of nickel underplating.

3.4.3 SMT Solder Balls

The socket is mounted to the PCB by SMT, with a PCB solder pad diameter of 0.64 mm.

Each solder ball on the socket is tin and lead (63/37 \pm 5%) with a diameter of 0.76 mm.

The contact must include a solder barrier feature to prevent solder from wicking up into the contact mating area during solder reflow.

The Socket 940 solder ball field must meet the co-planarity requirement of 0.20 mm.

3.5 Socket Actuation Lever

The socket incorporates a stainless steel lever to the right side of the cam box for actuating and de-actuating the socket contacts with the package pins. This actuation lever provides the mechanical advantage to easily actuate the socket in an OEM high-volume manufacturing environment and also facilitates toolless socket actuation and de-actuation operations by the end-user.

3.5.1 Package Insertion and Extraction Force

With the actuation lever in the *open* position, the package insertion and extraction forces, conceptually, are *zero*. These insertion and extraction forces must not exceed 2 kgf in actual applications.

3.5.2 Socket Retention Force

With the actuation lever in the *closed* position, the force required to extract the package pins out of the socket contacts must be a minimum of 0.013 kgf per pin.

3.5.3 Locking Latch

The socket cover incorporates a latch mechanism to lock the lever in the *closed* position after the socket contacts are mated with the package pins. Support tab(s) are added to the socket cover to cradle the actuation lever in the *closed* position. The tab(s) prevent the actuation lever from contacting the PCB.

3.5.4 Lever Actuation and De-Actuation Force

The force required to actuate or de-actuate the lever must be less than 3.6 kgf.

3.5.5 Pin Field Actuation Displacement

The package pins must be displaced less than 1.0 mm during socket actuation or de-actuation.

3.6 Socket Durability

The socket must maintain electrical and mechanical integrity after 50 actuation and de-actuation cycles.

3.7 Visual Inspection

All visual inspections shall be at 1X magnification, except for solder balls, which must be inspected at 5X magnification.

3.7.1 Solder Balls

There can be no missing, malformed, damaged, or misaligned solder balls attached to the contacts.

3.7.2 Contacts

There can be no missing or damaged contacts that prevent the socket from functioning properly. Contact mating surface must not be missing gold plating.

3.7.3 Cover and Base

There can be no cracks or flashing visible on the socket cover and base. All tabs for securing the socket cover to the base must not be damaged or missing. The socket cover must fit properly on the socket base with no visible gap between them. The lever latch cannot be damaged or malformed.

3.7.4 Actuation Lever

The actuation lever cannot be damaged, malformed, or missing.

4 Socket Electrical Requirements

This chapter describes the contact current rating, inductance, capacitance, differential impedance, propagation delay, crosstalk, dielectric withstanding voltage, and insulation resistance of the Socket 940.

4.1 Contact Current Rating

The contact must be rated at a current rating of 1.5 A per contact, with less than 30°C temperature rise with a minimum of six rows of mated contacts and pins energized.

4.2 Low Level Circuit Resistance (LLCR)

Contact resistance applies to the mounted socket with actuated package pin, and includes the bulk resistance of the contact, solder ball, package pin, and the interface resistance between the contact and the package pin, but does not include the package internal trace resistance.

Initial Circuit Resistance

Initial circuit resistance shall be measured immediately after the first mating of the package pins to the socket contacts. Two hundred daisy-chained pairs (400 contact locations) must be measured per socket sample. Initial LLCR must not exceed 25 mΩ per contact when mated with Kovar pins, based on measurements made on a daisy-chained pair of contacts.

Final Circuit Resistance

Final circuit resistance shall be measured after the mechanical and environmental testing of the mated package and socket is complete. The same 200 daisy-chained pairs (400 contact locations) must be measured per socket sample. Final LLCR must not exceed 25 mΩ per contact when mated with Kovar pins, based on measurements made on a daisy-chained pair of contacts.

4.3 Inductance

The mated, partial self-inductance of a single pin must be less than 4 nH.

The mated-loop inductance of two nearest pins must be $3 \text{ nH} \pm 10\%$.

The mated partial-loop inductance matrix of three neighboring pins must be $3 \text{ nH} \pm 10\%$.

***Note:** Measurements are made at frequencies of 500 MHz and 2 GHz.*

4.4 Capacitance

The mated capacitance between two nearest pins must be less than 1 pF.

The mated capacitance matrix of three neighboring pins must be less than 1 pF.

Note: Measurements are made at frequencies of 500 MHz and 2 GHz.

4.5 Differential Impedance

The differential (or odd mode) impedance for three, mated-pins configuration (one pin as the voltage/current reference—S1, S2, and G) must be $100\ \Omega \pm 10\%$ between the two nearest pins. If the Time Domain Method is used, the signal must have a rise time of 150 ps for the signal amplitude to go from 10% to 90%.

4.6 Propagation Delay

The propagation delay skew among single-ended signals must be less than 10 ps, plus a maximum measurement error of 3 ps.

The propagation delay skew among differential signal pairs must be less than 10 ps, plus a maximum measurement error of 3 ps.

4.7 Crosstalk

Crosstalk between the nearest single-ended and differential signals must be measured and compared to results from the measured partial-loop inductance and the Maxwell capacitance matrices.

4.8 Dielectric Withstanding Voltage (DWV)

The contact-to-contact dielectric withstanding voltage between randomly selected adjacent lateral, diagonal, and vertical contacts must be a minimum of 650 Vac.

4.9 Insulation Resistance

The contact-to-contact insulation resistance between randomly selected adjacent lateral, diagonal, and vertical contacts must be a minimum of 1000 M Ω .